• When
$$f_{xy} = f_{yx}$$
? Clairant's thun: If f is C²-function
 $f_{xy} = f_{yx}$.
• C²-function =) coun change the order of partial derivatives
up to order r.
• differentiability: \supseteq linear approximation
 $LCRI \ s(1, SCR) = f(R) - LCR)$
 $\int_{imn} \frac{SCRI}{IR - BII} = 0$.
 $F_{rotic} IR - BII = 0$.
 F_{roti

To be differentiable,
$$\lim_{(x,y)\to(a,a)} \frac{f(x,y)}{f(x,y)(x,a,y)} = 0$$
.
15 and $\frac{f(x,y)}{f(x,y)-f(a,a)} = \lim_{(x,y)\to(x,a,y)} \frac{f(x,y)}{f(x,y)} = 0$.
15 and $\frac{f(x,y)}{f(x,y)-f(a,a)} = \lim_{(x,y)\to(x,y)\to(x,y)} \frac{f(x,y)}{f(x,y)}$
(x = r cos 0) = $\lim_{(x,y)\to(x,y)\to(x,y)\to(x,y)\to(x,y)\to(x,y)} \frac{f(x,y)}{f(x,y)}$
(x = r cos 0) = $\lim_{(x,y)\to$

différenticbility implies: information from coordinate directions ()X; roa tell information on every direction Genry 0 0 If $f(\vec{x})$ is differentiable of \vec{a} , then $f(\vec{x})$ is continuous of \vec{a} . Thm (proof) Suppose f(x) is differentiable at a. Then I linear approximation $L(\vec{x}) = f(\vec{a}) + \sum_{i=1}^{n} \frac{\partial f_i}{\partial x_i} (\vec{a}) (x_i - 0_i)$ $\int \left\{ \frac{1}{x} + \frac{1}{x} \right\} = 0$ $= \frac{(im \epsilon(\vec{x}) = im \frac{\epsilon(\vec{x})}{|\vec{x} - \delta||} \cdot \frac{im |\vec{x} - \delta||}{|\vec{x} - \delta||}$ = 0 f(x) = L(x) + f(x) $lim_f(\vec{x}) = lim_L(\vec{x}) + \ell(\vec{x})$ $\vec{x} = \vec{x} - \vec{a}$ x-)E $= \lim_{x \to a} L(x) + \lim_{x \to a} E(x)$

 $= \lim_{x \to a} \left(f(\vec{a}) + \sum_{i=1}^{n} \frac{1}{x_i} (x_i - \alpha_i) \right) + 0$ = f(a). : (in f(x) = f(a) hence f is continuny at t. differentiability = linear approximation What if f is linear? Rmk $f(\vec{x}) = C + b_1 x_1 + \cdots + b_n x_n$ $\partial f(\bar{x}) = b_i \quad \forall \bar{x} \in \mathbb{R}^n.$ $L(\hat{x}) = f(\hat{a}) + \Sigma \frac{1}{2k} \cdot (\hat{a})(x_{1} - o_{k})$ $= f(\hat{\alpha}) + \Sigma b_{\hat{\alpha}} (x_{\hat{n}} - a_{\hat{n}})$ $= C + b_1 x_1 + \cdots + b_n x_n = f(\vec{x})$ f(x) = f(x) - L(x) = 0.out any point is The (ineurizeth of f(x) L(x) = f(x) itself.

If f,g; R(SR) -> IR are differentialle Thm at $E \in \Omega$, then $Df(x) \pm g(x)$, cf(x), f(x)g(x) are differentiable of α . J If g(ā) ≠ v, fhen f(x)/g(x) is differentiable of R. B Let h(x) be a one-variable function. Suppose h is differentiable at f(E). Then h f is differentiable at G. A formule for computing differente of Rink composition of two functions is called a chain rule. 3) is special rose of chaîn nule. We will see fuis loter. Cproof of Thm) Similar to one-voriable case. By the Thin, we can produce many examples of d'ifferentioble functions. We know [constant function f(x) = CCoordinate function $f(x) = X_i$

are differentiable.
By the frearem,
polynovirials of
$$f(x,y,z) = x^3z + xyz + y + 1$$

rational functions of x^{5y+2z}
 $xz + y + z$
 $y + z + z$
 $x + z + z$
 x

at (","). ヨチレ 5 If all dt can be easily checked that they are continuous, the theorem implies the differentiability of f. eg f(x.y.21= x extra - Log (x+2) Domain f = ((x, y+2) E (RS) X+2>0 } îs open. Xt2 #= exty + xexty all are continuous $\frac{\partial f}{\partial y} = \chi e^{\kappa f \cdot y}$ on the clomain of f 27 = - ++2 if is C' 5 f is different lable.

Cproof of Thun)
We will prive for 2-variable function flog).
Similar prior works for N-variables.
iden: NVT.
Supple ca.b)
$$\in \Omega$$
.
Choose $\delta > 0$ s.l. B_{δ} (n.l) $\leq \Omega$.
(Recould Ω is open).
For (Ky) $\in B_{\delta}$ (0.b),
f(X,y) $-f(a.b)$
 $= f(X,y) - f(x,b) + f(xb) - f(a.b)$
(MVT)
 $= f_{\delta}(X,b)(y-b) + f_{\delta}(X,b) - f(a.b)$
(MVT)
 $= f_{\delta}(X,b)(y-b) + f_{\delta}(X,b) - f(a.b)$
 $(x,b)(y-b) + f_{\delta}(X,b) - f(a.b)$
 $(x,b)(x-a)$
 $h = a.x$.
We need to show that
 $(in \frac{e(R)}{||R-\delta||} = 0$.

where
$$L(x, y) = f(a,b) + \frac{34}{6x} (a,b)(x,a) + \frac{34}{6y} abg b
 $2(x,y) = f(x,y) - L(x,y)$
 $\frac{g(x,y)}{||x - a||}$
 $= \int \frac{f(x,y) - f(a,b) - f_x(a,b)(x-a) - f_y(b,b)(y,y)}{\int (x-a)^2 + (y,b)^2}$
 $= \int \frac{f_y(x,b)(y,b) + f_x(b,b)(x-a) - f_x(a,b)(x-a)}{\int (x-a)^2 + (y,b)^2}$
 $= \int \frac{f_y(x,b)(y,b) + f_x(b,b)(x-a) - f_x(a,b)(y,b)}{\int (x-a)^2 + (y,b)^2}$
 $= \int \frac{f_y(x,b) - f_y(a,b)(y,b) + (f_x(b,b) - f_xa)}{\int (x-a)^2 + (y,b)^2}$
 $= \int \frac{f_y(x,b) - f_y(a,b)(y,b)}{\int (x-a)^2 + (y,b)^2}$
 $= \int \frac{f_y(x,b) - f_y(a,b)(x,b)}{\int (x-a)^2 + (y,b)^2}$$$

Take (xy) -> (n.b), then $(x \in 1, ch \cdot b) \longrightarrow (a \cdot b)$ By continuity of fx, fy, MaRHS -> 0 Or. y -> (a.6) By scundwich them, lim<u>E(x.y)</u> = υ. (xy) [[(xy)-(a.)] -1 (0.6) : f is differentiable out (a,b) \square Gradient & directional derivative SIEIR" open a= S. f; S-)K. Det The gradient vector of f at a 's $\nabla f(\vec{x}) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}(\vec{x})\right)$ (a 2t) f(x.y)= x2+2xy ध्व fx = 2xtry. fy = 2x Rf = (2x+ry, 2x) [/.2) = (6, 2]

Using Of, linearization of for a Rink can be written as $L(\hat{x}) = f(\hat{a}) + \hat{\sum} \frac{\partial f}{\partial x_i} (\hat{a}) (x_i - a_i)$ $= f(\vec{n}) + \gamma f(\vec{n}) \cdot (\vec{x} - \vec{n})$ $\stackrel{(i)}{\longrightarrow} \stackrel{(i)}{\longrightarrow} \stackrel{(i)}{\longrightarrow} \stackrel{(i)}{\longrightarrow} (x_{i} - \alpha_{i}, \dots, x_{in} - \alpha_{i})$ SLEIR, open. aER. firm. Def Let $\tilde{u} \in \mathbb{R}^n$ be an unit vector. Line. $(|\tilde{u}| = 1)$ The directional derivative of f in the direction it at & $D_{u}f(\vec{a}) = \lim_{t \to 0} \frac{f(\vec{a}+t\vec{u}) - f(\vec{a})}{t}$ = the rote of change of f in the direction of it of the point a. $e_{i} = (o, \dots, l, \dots o) \in \mathbb{N}^{n}$ Rmk Then $\partial f/\partial x_i$ $(a) = De_i f(\hat{a})$.

Suppose f's d'ifferentiable at à. UER unit vector (hm then $Daf(\bar{\kappa}) = \nabla f(\bar{\kappa}) \cdot \bar{u}$. Let f(x,y) = Sin'(x). eq Find the vote of change of f at (I_{1}, J_{2}) in the direction of $\overline{V} = (1, -1)$. (Recall of $\overline{\mathcal{V}}(4)$) eik", the direction $\overline{\mathcal{V}}$ is defined to be the unit rector $\overline{\mathcal{V}}_{[[\overline{\mathcal{V}}][]}$ $\frac{\sqrt{10}}{100} = \frac{1}{10} (1.7) = \frac{1}{10}.$ (S) Ve want compute Dit (1.JZ). Recall that $(\sin^2 2)' = \frac{1}{\sqrt{1-2^2}}$. Hence $\frac{\partial f}{\partial x} = \frac{1}{y} \cdot \frac{1}{\sqrt{1 - (\frac{x}{y})^2}}, \quad \frac{\partial f}{\partial y} = -\frac{x}{y^2} \cdot \frac{1}{\sqrt{1 - (\frac{x}{y})^2}}$ Note that of , it are with continuing at (1. 27

: f is C' at (1.52). : f is different lable at (1.52). By Thm, Dat (1.52) $= \nabla f(1.\sqrt{2}) \cdot \vec{u}$ $= \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{1-(\frac{1}{\sqrt{2}})^2}} \right)^{-\frac{1}{2}} \cdot \frac{1}{\sqrt{1-(\frac{1}{\sqrt{2}})^2}}$ •(志,-志) $= (\frac{1}{4}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2}) \cdot (\frac{1}{4}, \frac{1}{2})$ Cproof of Theorem) : differentiable = Dafia) = Dfia)· i. Let LCR) be the lineorization of f(R) at a. f(x) = L(x) + f(x) $= f(\vec{\alpha}) + \nabla f(\vec{\alpha}) \cdot (\vec{\chi} - \vec{\alpha}) + \mathcal{E}(\vec{\chi}).$

If we let $\vec{x} = \vec{a} + t\vec{u}$ $f(\vec{a} + t\vec{u}) = f(\vec{a} + \tau \tau f(\vec{a}) \cdot (t\vec{u}) + f(\vec{a} + t\vec{u})$ $\frac{\partial c^{i}f(\vec{k})}{-1im} + \frac{f(\vec{a} + t\vec{a}) - f(\vec{k})}{t}$ $= \lim_{t \to 0} \frac{\nabla f(\vec{c}) \cdot (t\vec{u}) + \varepsilon(\vec{c} + t\vec{u})}{t}$ $= \nabla f(\vec{a}) \cdot \vec{u} + \lim_{t \to 0} \frac{f(\vec{a} + t\vec{u})}{t}$ By differentiability of f at \vec{a} , $1im \frac{1E(\vec{x})}{|\vec{x}-\vec{a}|} = 0$. In particular, $\vec{x} + \vec{a} ||\vec{x}-\vec{a}|$ $\frac{\lim_{t \to 0} |\underline{\varepsilon}(\vec{a} + t\vec{u})|}{|\vec{a} + t\vec{u} - \vec{a}||} = 0$ $= 1 \text{im} | \epsilon(\alpha + t\alpha)$) (((171) =) セー 11 七山 (.e. 12m) { (a+ta) | +->> 1t1

direction of - $\nabla f(E)$. at a rote of change 11 Df (E) 11, prop (properties of gradient) fig: S→R, differentiable. $O \nabla (f \pm g) = \nabla f \pm Vg$ $\mathcal{D}(cf) = c \mathcal{D}f.$ $\Im \nabla(f/g) = \frac{g\rho_f - f\rho_g}{g^2} \quad if \quad g \neq 0.$ (prosf) follows easily from the properties of portial differentiations. In the definition of Diff, we assumed Rmf The is a unit vector. However, we can drop this condition. T.l. consider any vector 7 of any legith. we can define $D_{\vec{v}}f(\vec{k}) = \lim_{t \to 0} \frac{f(\vec{k}+t\vec{v}) - f(\vec{a})}{t}$

and $D_{\vec{v}}f(\vec{k}) = Df(\vec{k})\cdot\vec{v}$. Note that Dort f(a) = C. Drf(h)